

# Performance analysis of the SO/PHI software framework for on-board data reduction

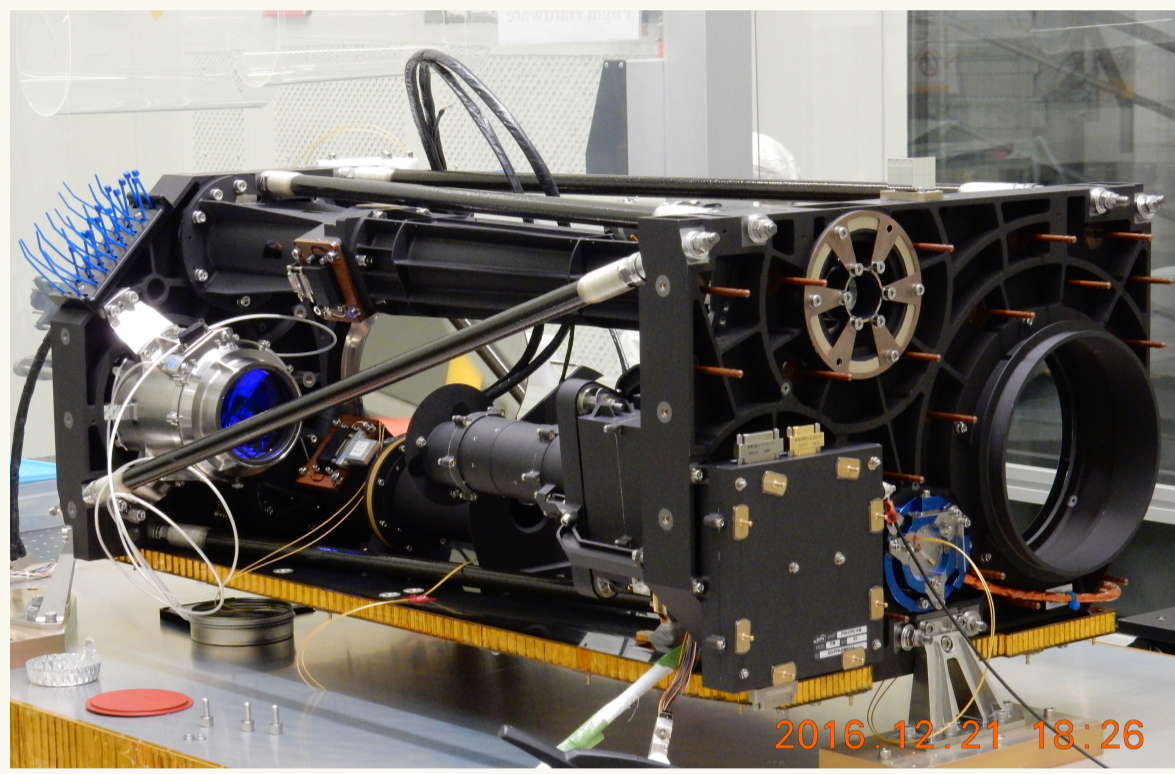
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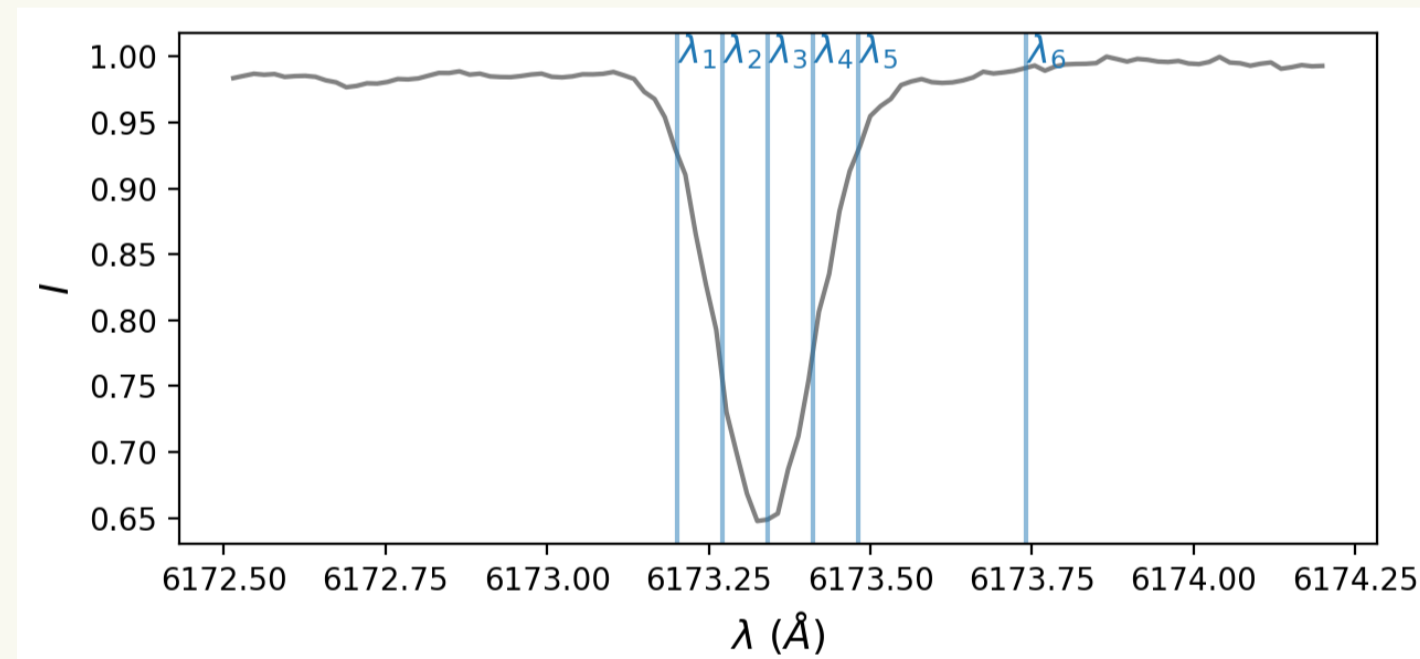
## PHI on the Solar Orbiter

- **Solar Orbiter:** A mission to orbit the Sun in highly elliptical orbits, leaving the ecliptic.
- **SO/PHI:** The first solar imaging spectropolarimeter on a deep space mission.



SO/PHI flight model O-unit.

- **Instrument principle:** SO/PHI is aiming to infer photospheric  $\vec{B}$ ,  $v_{LOS}$  and  $T$  by using Zeeman and Doppler effects. It takes time-series of images sampling the FeI 6173 Å absorption line at 6 wavelengths, in 4 polarisation states.



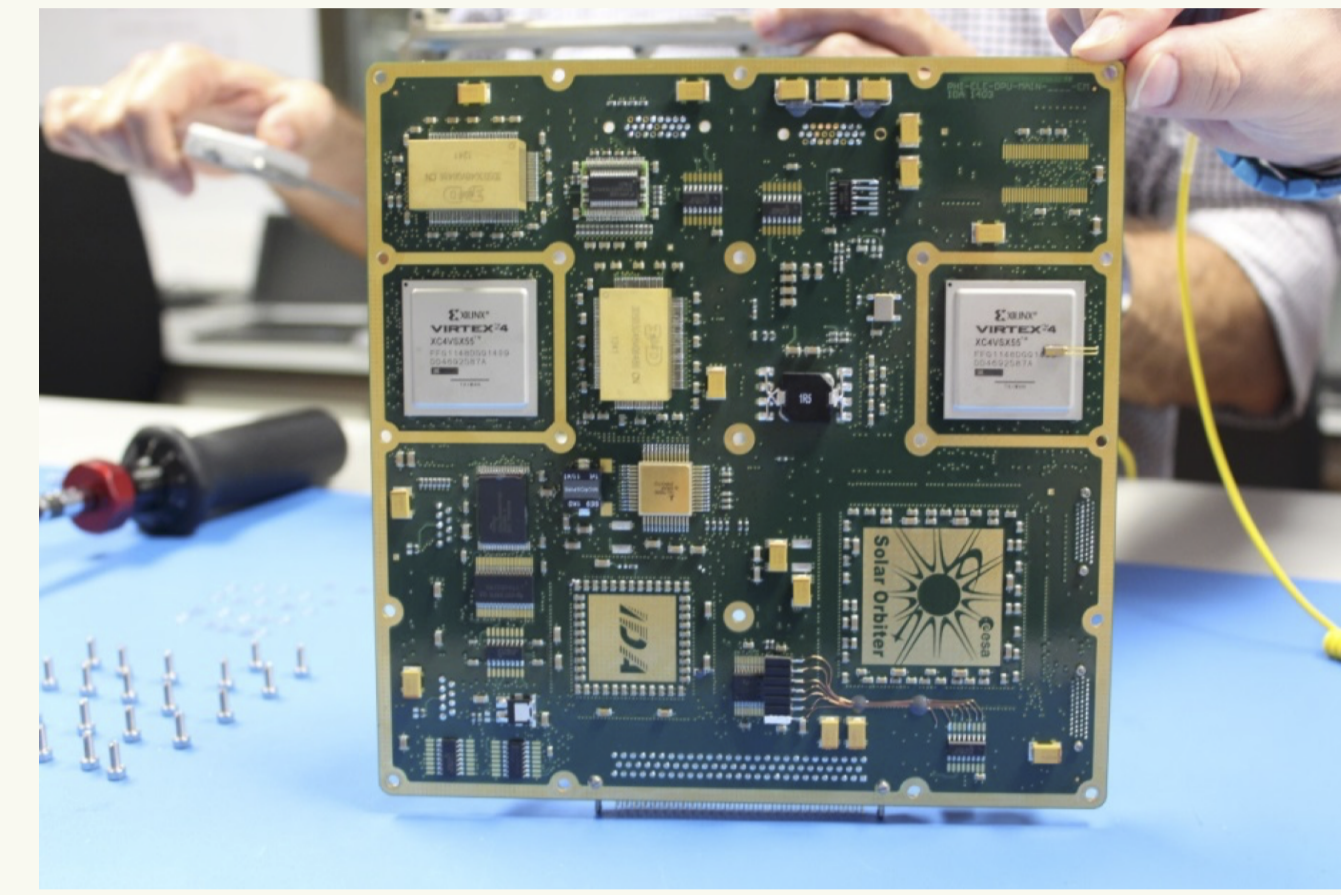
Sampling of the absorption line by SO/PHI.

- To meet some of the challenges imposed by SO, i.e. dynamic environment and low data rates, SO/PHI does **full on-board science data processing**: data pre-processing (removing the instrumental effects and polarimetric demodulation), and infers the physical parameters (through the inversion of the radiative transfer equation, RTE).

## References

- [1] K. Albert, J. Hirzberger, D. Busse, et al. Autonomous on-board data processing and instrument calibration software for the SO/PHI. *Proceedings SPIE*, 707:10707 – 10707 – 9, 2018.
- [2] S.K. Solanki, J.C. del Toro Iniesta, J. Woch, et al. The Polarimetric and Helioseismic Imager. *Astronomy and Astrophysics*. Submitted.
- [3] Daniel Müller, Richard George Marsden, OC St Cyr, et al. Solar orbiter. *Solar Physics*, 285(1-2):25–70, 2013.

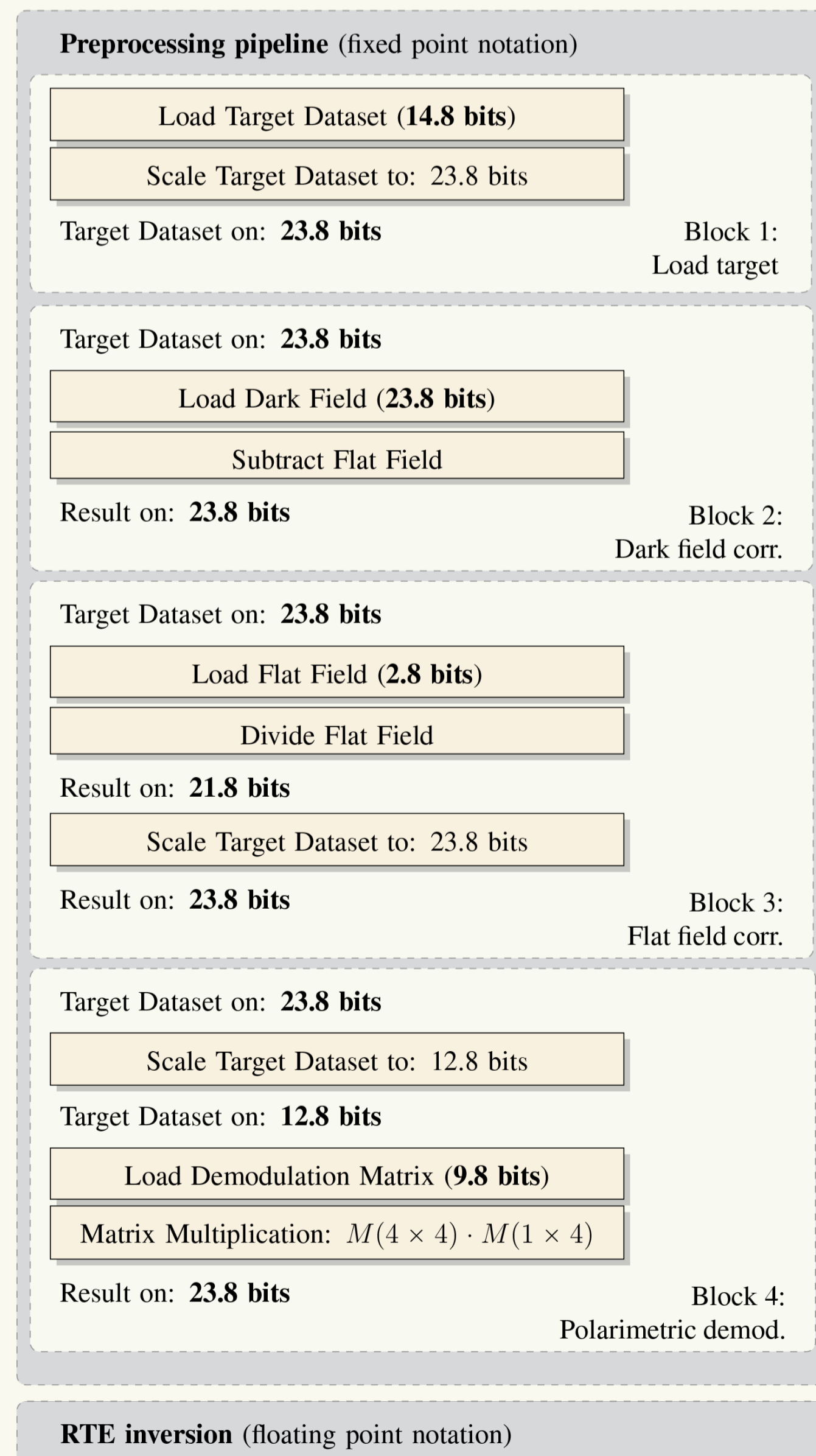
## Data processing system



The SO/PHI DPU.

- The data processing is implemented on a custom DPU, accelerated with 2 FPGAs reconfigured in flight. Pipelines are built in the microprocessor, using FPGA functions.
- To save resources the pre-processing uses a **24.8 bits fixed point notation**. To maintain accuracy the data is scaled at each step of the processing.
- Test pipeline:  

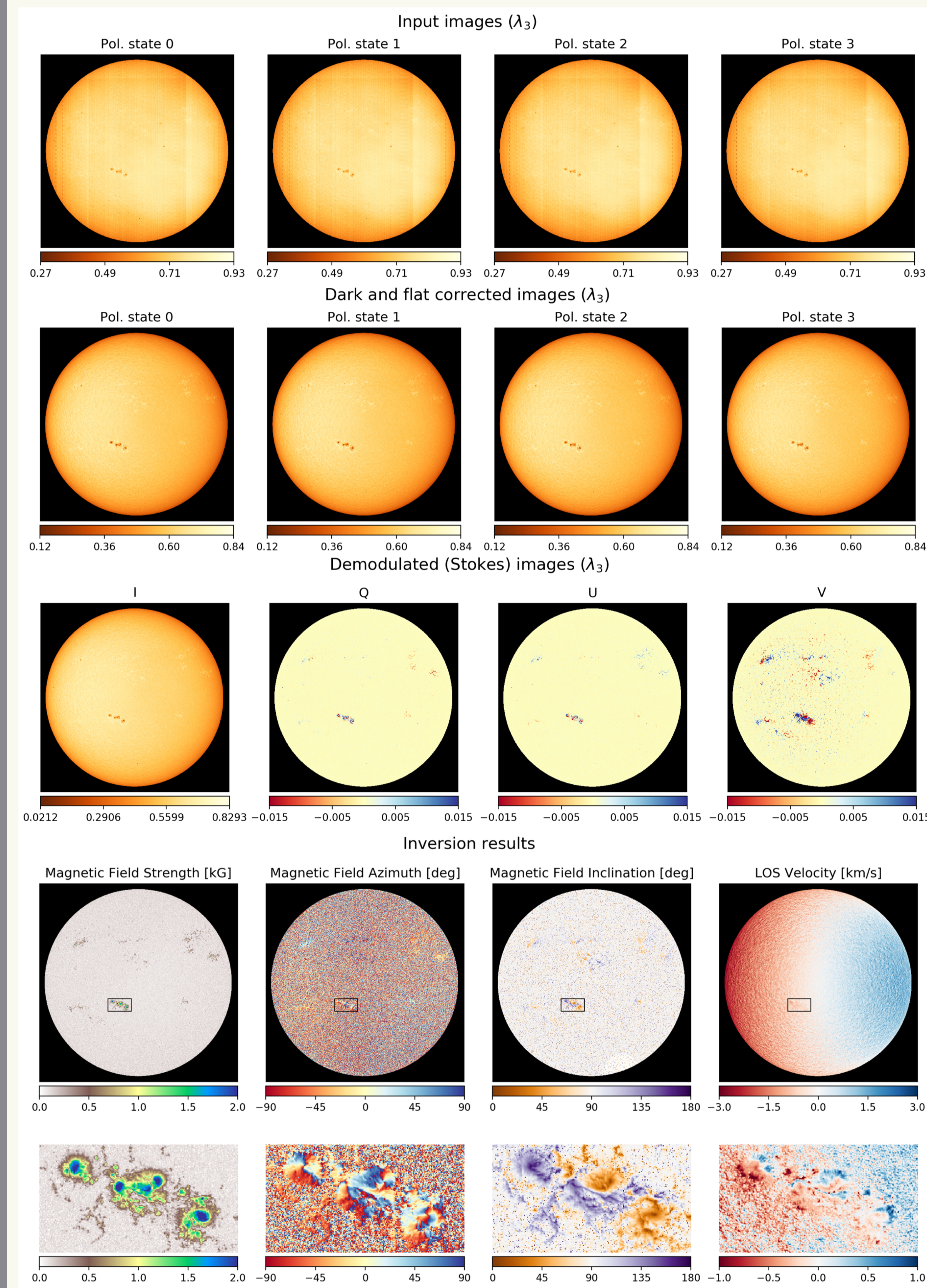
$$S_{\lambda}(x, y) = D(x, y) \cdot [(I_{\lambda}^{obs}(x, y) - I^{dark}(x, y)) / I^{flat}(x, y)]$$



Data accuracy is controlled in the pipeline.

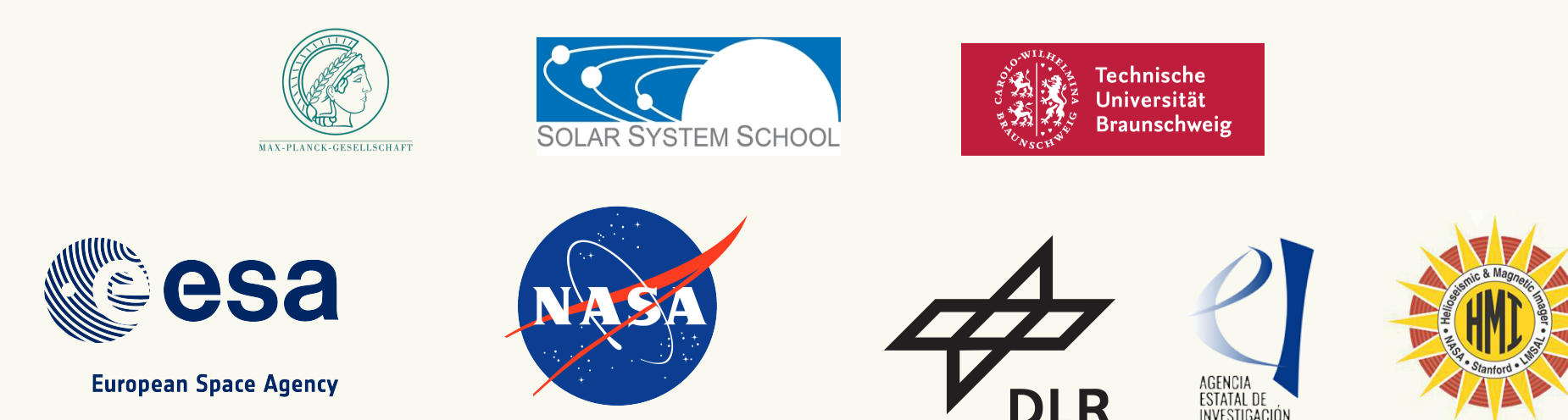
## Science data processing

- The results of the SO/PHI pipeline are compared to reference pipeline results calculated in floating point.
- The inversion of the RTE is done on ground for an impression.



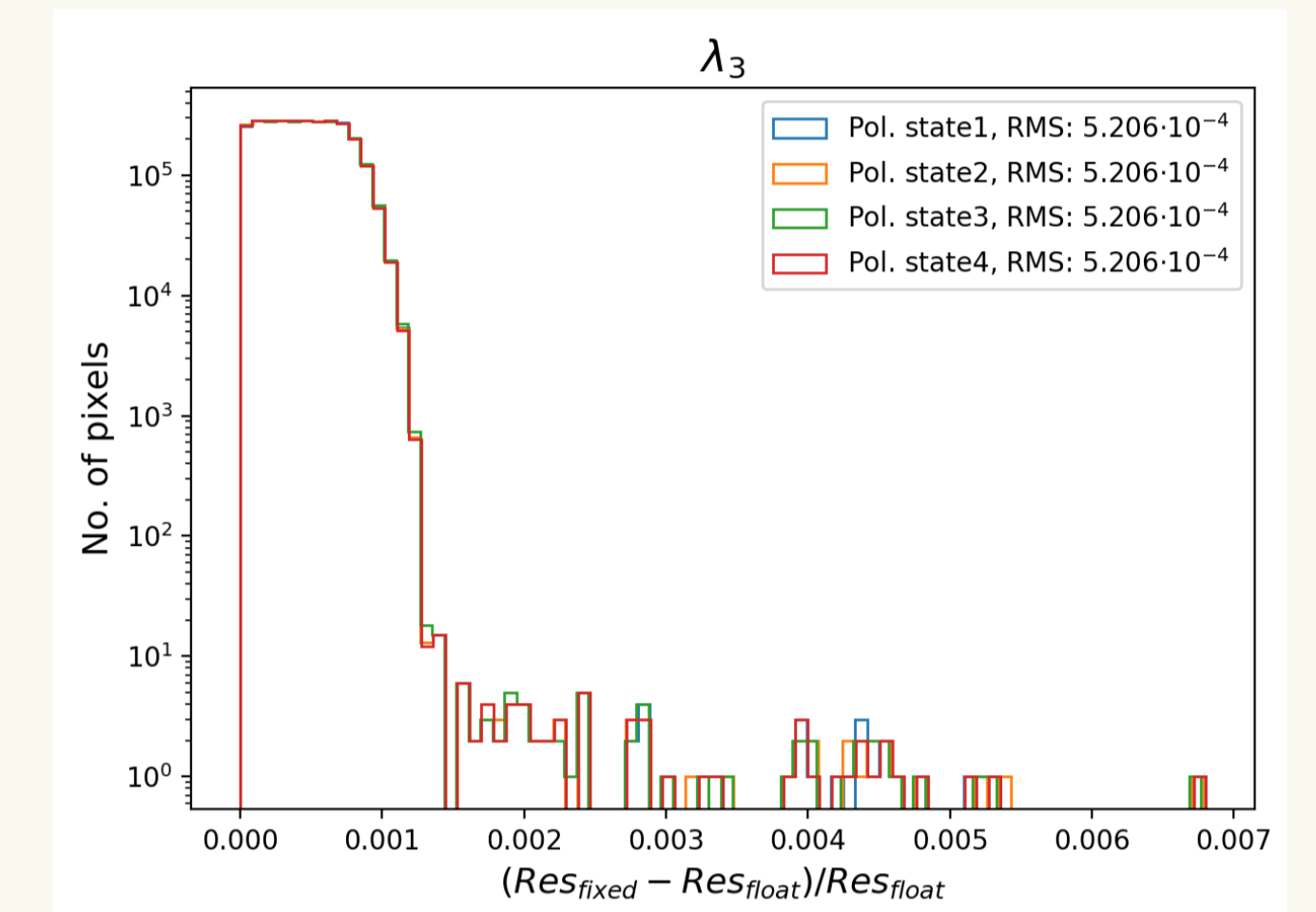
The input data, and the partial results of the tested pipeline.

## Acknowledgments



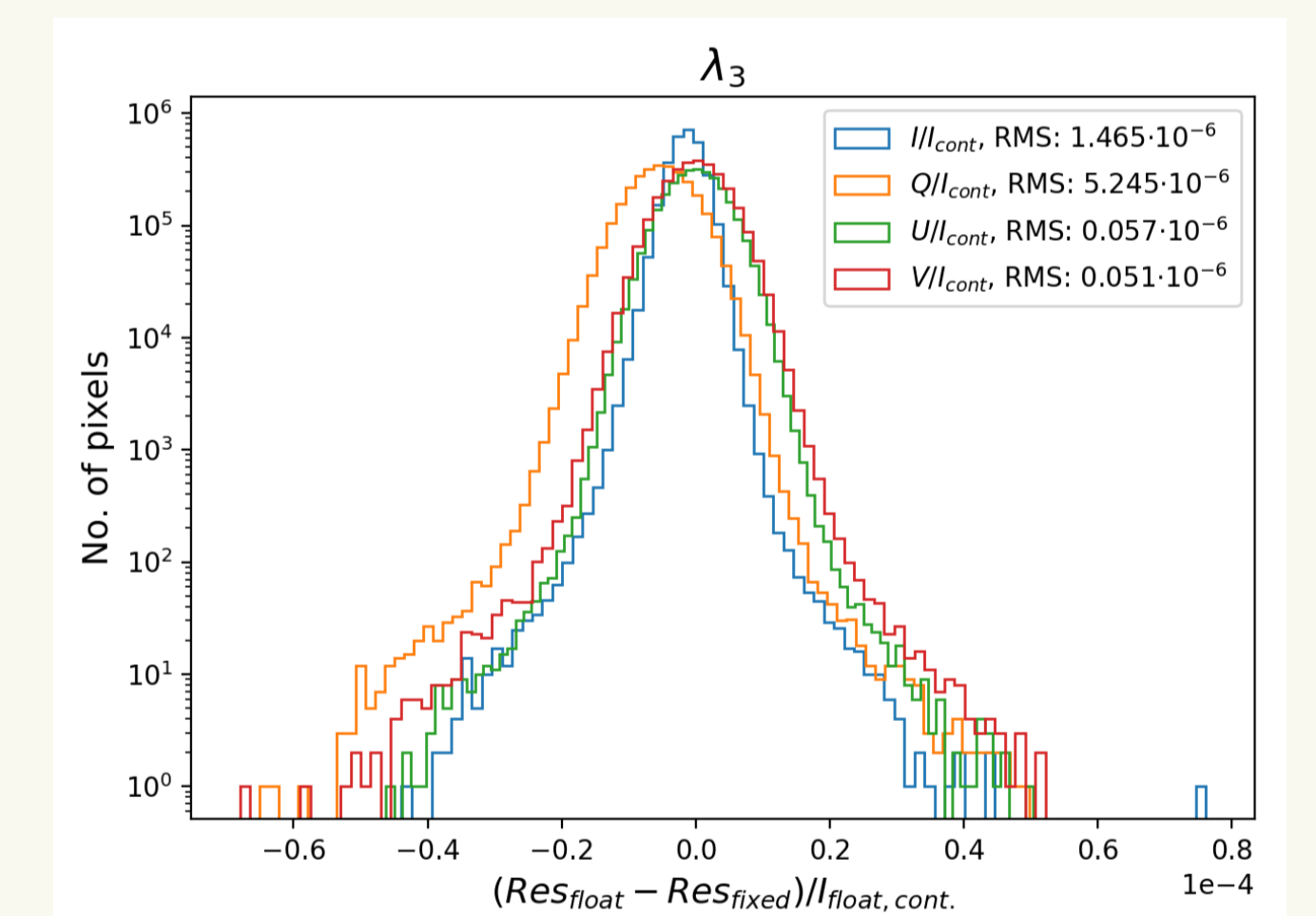
## Results

- The flat field division induces uniform errors in the whole data set, with a  $5 \cdot 10^{-4}$  RMS.



Histogram of errors after flat field division.

- The errors after the polarimetric demodulation decrease because in polarimetry we calculate the difference of signals. The requirement is  $10^{-3}$  sensitivity. The error RMS is in the order of  $10^{-6}$ .



Histogram of errors after polarimetric demodulation.

- The inferred physical parameters have inaccuracies with an RMS of 0.14 G,  $2^\circ$  and  $0.04^\circ$  in the  $\vec{B}$  strength, azimuth and inclination (calculated over strong magnetic regions). The  $v_{LOS}$  error RMS is  $7 \cdot 10^{-3} \text{ ms}^{-1}$  over the full disk.

## Conclusions

- SO/PHI executes part of the data processing in fixed point notation to save resources.
- The fixed point notations introduce errors far below the instrument requirements, leaving a large margin for other error sources.
- The analysis of  $\mathcal{F}$  domain processing is ongoing.